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This course presents an overview of robotics in practice and research with topics including vision, motion planning, mobile mechanisms, kinematics, inverse kinematics, and sensors. In course projects, students construct robots which are driven by a microcontroller, with each project reinforcing the basic principles developed in lectures.

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as kinematic chains. Topics covered include the concept of a robot ' s configuration space and degrees of freedom, static grasp analysis, the description of rigid body motions, kinematics of open and closed chains, and the basics of robot control.

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For senior-year or first-year graduate level robotics courses generally taught from the mechanical engineering, electrical engineering, or computer science departments. Since its original publication in 1986, Craig's Introduction to Robotics: Mechanics and Control has been the market's leading textbook used for teaching robotics at the university level.

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Over all, I would say this is the best source for understanding mechanics and control theory as it relates to robotics motion. It really gets into the details that books on the subject of computational robots such as "Introduction to Autonomous Mobile Robots" and "Computational Principles of Mobile Robotics" simply do not have the room to accommodate.

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