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Stability regions of
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systems. Abstract:
A topological and
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characterization of
the stability
boundaries for a

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A fairly large class of nonlinear autonomous dynamic systems is presented. The stability boundary of a stable equilibrium point is shown to consist of the stable manifolds of all the equilibrium points (and/or closed orbits) on the

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Regions as a
consequence of
parameter
variation. These
changes are
triggered by local
or global
bifurcations of the
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Abstract: The concept of a stability region (region of attraction) of nonlinear dynamical systems is widely accepted in many fields such as engineering and the sciences. When utilizing this concept, the Lyapunov function

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approach has been found to give rather conservative estimations of the stability regions of many nonlinear systems. In this paper we study the notion of a quasi-stability region and develop a comprehensive theory for it.

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Quasi-stability

*regions of
nonlinear*

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[Chiang, Hsiao-

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